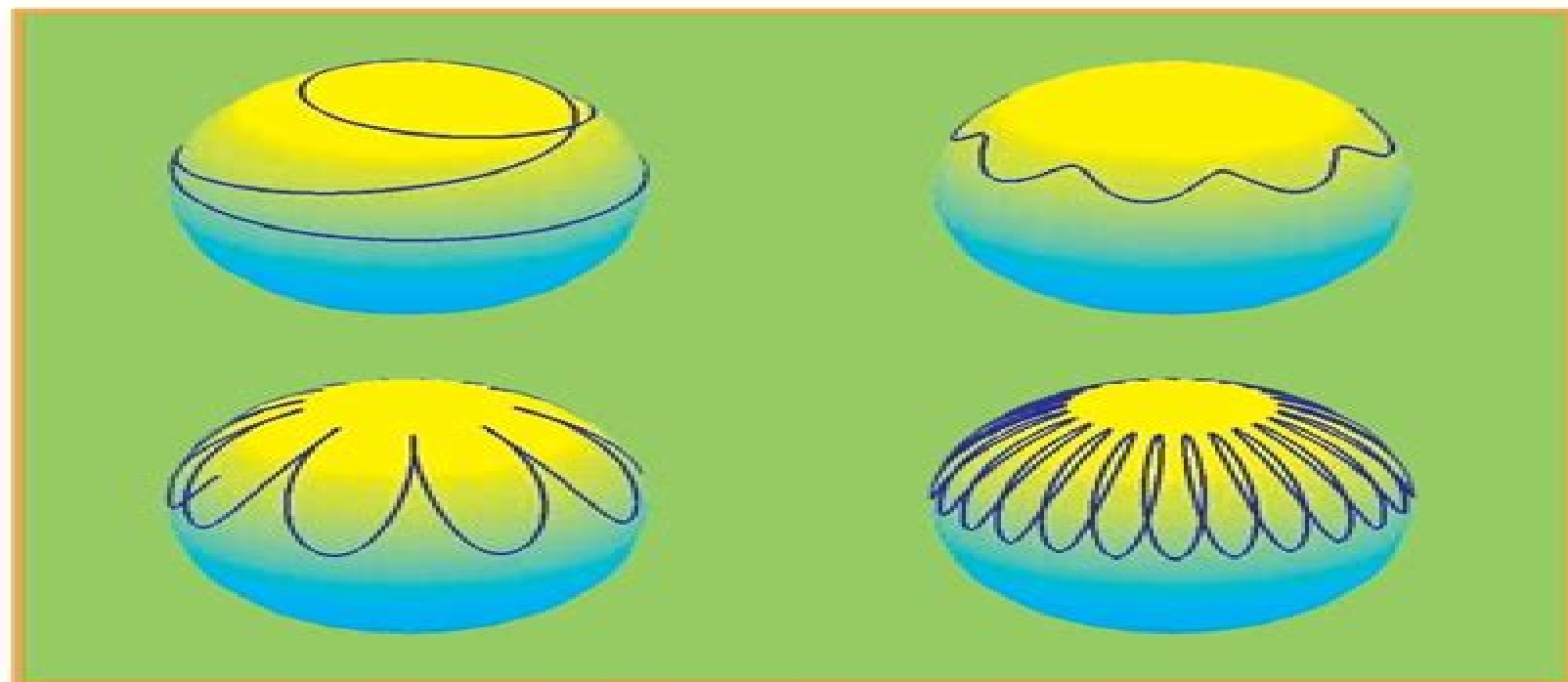


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Mathematics, Physics and Applications



Rigid Body Mechanics Mathematics Physics And Applications

Alexey Borisov, Ivan S. Mamaev



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Rigid Body Dynamics for Space Applications Vladimir Aslanov, 2017-04-22 *Rigid Body Dynamics for Space Applications* explores the modern problems of spaceflight mechanics such as attitude dynamics of re entry and space debris in Earth's atmosphere dynamics and control of coaxial satellite gyrostats deployment dynamics and control of a tether assisted return mission of a re entry capsule and removal of large space debris by a tether tow Most space systems can be considered as a system of rigid bodies with additional elastic and viscoelastic elements and fuel residuals in some cases This guide shows the nature of the phenomena and explains the behavior of space objects Researchers working on spacecraft attitude dynamics or space debris removal as well as those in the fields of mechanics aerospace engineering and aerospace science will benefit from this book Provides a complete treatise of modeling attitude for a range of novel and modern attitude control problems of spaceflight mechanics Features chapters on the application of rigid body dynamics to atmospheric re entries tethered assisted re entry and tethered space debris removal Shows relatively simple ways of constructing mathematical models and analytical solutions describing the behavior of very complex material systems Uses modern methods of regular and chaotic dynamics to obtain results

Movement Equations 3 Michel Borel, Georges Vénizélos, 2017-09-25 This volume is the focal point of the work undertaken in the previous volumes of this set of books the statement of the fundamental principle of the dynamics whose implementation according to two paths whose choice depends on the problem to be treated leads to equations of motion In order to achieve this it is treated first of all in the context of solids in their environment as a prerequisite for the formulation of the fundamental principle Then in addition to its use in some exercises the approach is illustrated by three particular cases The first is an example where it is developed end to end and addresses the two approaches that lead to the equations of motion The two other examples deal with two classical but important subjects the movement of the Earth according to the hypotheses that can be stated about it and Foucault's pendulum

Tensor Analysis for Engineers Mehrzad Tabatabaian, 2023-06-15 Tensor analysis is used in engineering and science fields This new edition provides engineers and applied scientists with the tools and techniques of tensor analysis for applications in practical problem solving and analysis activities It includes expanded content on the application of mechanical

stress transformation The geometry is limited to the Euclidean space geometry where the Pythagorean Theorem applies with well defined Cartesian coordinate systems as the reference Quantities defined in curvilinear coordinate systems like cylindrical spherical parabolic etc are discussed and several examples and coordinates sketches with related calculations are presented In addition the book has several worked out examples for helping the readers with mastering the topics provided in the prior sections

Geometric Science of Information Frank Nielsen,Frédéric Barbaresco,2025-10-19 The 3 volume set LNCS 16033 16035 constitutes the proceedings of the 7th International Conference on Geometric Science of Information GSI 2025 held in St Malo France during October 2025 The main theme of GSI 2025 was Geometric Structures of Statistical and Quantum Physics Information Geometry and Machine Learning FROM CLASSICAL TO QUANTUM INFORMATION GEOMETRY The 124 full papers included in the proceedings were carefully reviewed and selected from 146 submissions They were organized in topical sections as follows Part I Geometric Learning and Differential Invariants on Homogeneous Spaces Statistical Manifolds and Hessian information geometry Applied Geometry Informed Machine Learning Geometric Green Learning on Groups and Quotient Spaces Divergences in Statistics and Machine Learning Part II Geometric Statistics Computational Information Geometry and Divergences Geometric Methods in Thermodynamics Classical Geometric Mechanics Stochastic Geometric Dynamics Part III New trends in Nonholonomic Systems Learning of Dynamic Processes Optimization and learning on manifolds Neurogeometry Lie Group in Learning Distributions A geometric approach to differential equations Information Geometry Delzant Toric Manifold Integrable System

Rigid Body Dynamics Alexey Borisov,Ivan S. Mamaev,2018-12-03 This book provides an up to date overview of results in rigid body dynamics including material concerned with the analysis of nonintegrability and chaotic behavior in various related problems The wealth of topics covered makes it a practical reference for researchers and graduate students in mathematics physics and mechanics Contents Rigid Body Equations of Motion and Their Integration The Euler Poisson Equations and Their Generalizations The Kirchhoff Equations and Related Problems of Rigid Body Dynamics Linear Integrals and Reduction Generalizations of Integrability Cases Explicit Integration Periodic Solutions Nonintegrability and Transition to Chaos Appendix A Derivation of the Kirchhoff Poincar Zhukovskii and Four Dimensional Top Equations Appendix B The Lie Algebra e_4 and Its Orbits Appendix C Quaternion Equations and L A Pair for the Generalized Goryachev Chaplygin Top Appendix D The Hess Case and Quantization of the Rotation Number Appendix E Ferromagnetic Dynamics in a Magnetic Field Appendix F The Landau Lifshitz Equation Discrete Systems and the Neumann Problem Appendix G Dynamics of Tops and Material Points on Spheres and Ellipsoids Appendix H On the Motion of a Heavy Rigid Body in an Ideal Fluid with Circulation Appendix I The Hamiltonian Dynamics of Self gravitating Fluid and Gas Ellipsoids

Frontiers in Physics - 2019 Editor's Choice Alex Hansen,Thomas Beyer,Ewald Moser,Laura Elisa Marcucci,Ralf Metzler,Christian F. Klingenberg,James Sauls,José W. F. Valle,Jan De Boer,Dumitru Baleanu,Lorenzo Pavesi,Bretislav Friedrich,Christine Charles,Matjaž Perc,Jasper Van Der

Gucht,2020-05-19 Frontiers in Physics FPHY is now in its eighth year Up to last year the journal received a slowly increasing trickle of manuscripts and then during the summer Boom The number of manuscripts we receive started increasing exponentially This is of course a signal to us who are associated with the journal that we are on the right track to build a first rate journal spanning the entire field of physics And it is not the only signal We also see it in other indicators such as the number of views and downloads Impact Factor and the Cite Score Should we be surprised at this increase If I were to describe FPHY in one word it would be innovation Attaching the names of the reviewers that have endorsed publication permanently to the published paper is certainly in this class It ensures that the reviewers are accountable furthermore the level of transparency this implies ensures that any conflict of interest is detected at the very beginning of the process The review process itself is innovative After an initial review that proceeds traditionally the reviewers and authors enter a back and forth dialog that irons out any misunderstanding The reviewers retain their anonymity throughout the process The entire review process and any question concerning editorial decisions is fully in the hands of active scientists The Frontiers staff is not allowed to make any such decision They oversee the process and make sure that the manuscript and the process leading to publication or rejection upholds the standard FPHY is of course a gold open access journal This is the only scientific publication model that is compatible with the information revolution A journal s prestige is traditionally associated with how difficult it is to publish there Exclusivity as criterion for desirability is a mechanism we know very well from the consumer market However is this criterion appropriate for scientific publishing It is almost by definition not possible to predict the importance of a new idea otherwise it would not have been new So why should journals make decisions on publishing based on predicting the possible importance of a given work This can only be properly assessed after publication Frontiers has removed importance from the list of criteria for publication That the work is new is another matter the work must be new and scientifically correct It would seem that removing the criterion of importance would be a risky one but it turns out not to be The Specialty Chief Editors who lead the 18 sections that constitute FPHY have made this selection of papers published in FPHY in 2019 We have chosen the papers that we have found most striking Even though this is far from a random selection they do give a good idea of what FPHY is about Enjoy We certainly did while making this selection Professor Alex Hansen Field Chief Editor

Rigid Body Dynamics Hamad M. Yehia,2022-06-27 This monograph provides a complete and up to date examination of rigid body dynamics using a Lagrangian approach All known integrable cases which were previously scattered throughout the literature are collected here for convenient reference Also contained are particular solutions to diverse problems treated within rigid body dynamics The first seven chapters introduce the elementary dynamics of the rigid body and its main problems A full historical account of the discovery and development of each of the integrable cases is included as well Instructors will find this portion of the book well suited for an undergraduate course having been formulated by the author in the classroom over many years The second part includes more advanced topics and some of the author s original

research highlighting several unique methods he developed that have led to significant results Some of the specific topics covered include the twelve known solutions of the equations of motion in the classical problem which has not previously appeared in English before a collection of completely new integrable cases and the motion of a rigid body around a fixed point under the action of an asymmetric combination of potential and gyroscopic forces Rigid Body Dynamics will appeal to researchers in the area as well as those studying dynamical and integrable systems theory *Handbook of Robotic and Image-Guided Surgery* Mohammad Hossein Abedin Nasab,2019-09-25 Handbook of Robotic and Image Guided Surgery provides state of the art systems and methods for robotic and computer assisted surgeries In this masterpiece contributions of 169 researchers from 19 countries have been gathered to provide 38 chapters This handbook is 744 pages includes 659 figures and 61 videos It also provides basic medical knowledge for engineers and basic engineering principles for surgeons A key strength of this text is the fusion of engineering radiology and surgical principles into one book A thorough and in depth handbook on surgical robotics and image guided surgery which includes both fundamentals and advances in the field A comprehensive reference on robot assisted laparoscopic orthopedic and head and neck surgeries Chapters are contributed by worldwide experts from both engineering and surgical backgrounds *Movement Equations 1* Michel Borel, Georges Vénizélos,2016-09-16 The set of books on Mechanical Engineering and Solid Mechanics of which this book is the first volume is an essential tool for those looking to develop a rigorous knowledge of the discipline whether students professionals in search of an approach to a problem they are dealing with or anyone else interested This volume deals with the elements required for establishing the equations of motion when dealing with solid bodies Chapter 1 focuses on the systems of reference used to locate solid bodies relative to the observer and demonstrates how to describe their position orientation and evolution during their motion Chapter 2 introduces descriptors of motion such as velocity and acceleration and develops the concept of torsor notation in relation to these descriptors Finally Chapter 3 concerns the notions of mass and inertia as well as the kinetic torsor and dynamic torsor which consolidate the kinematic and kinetic aspects in a single concept

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