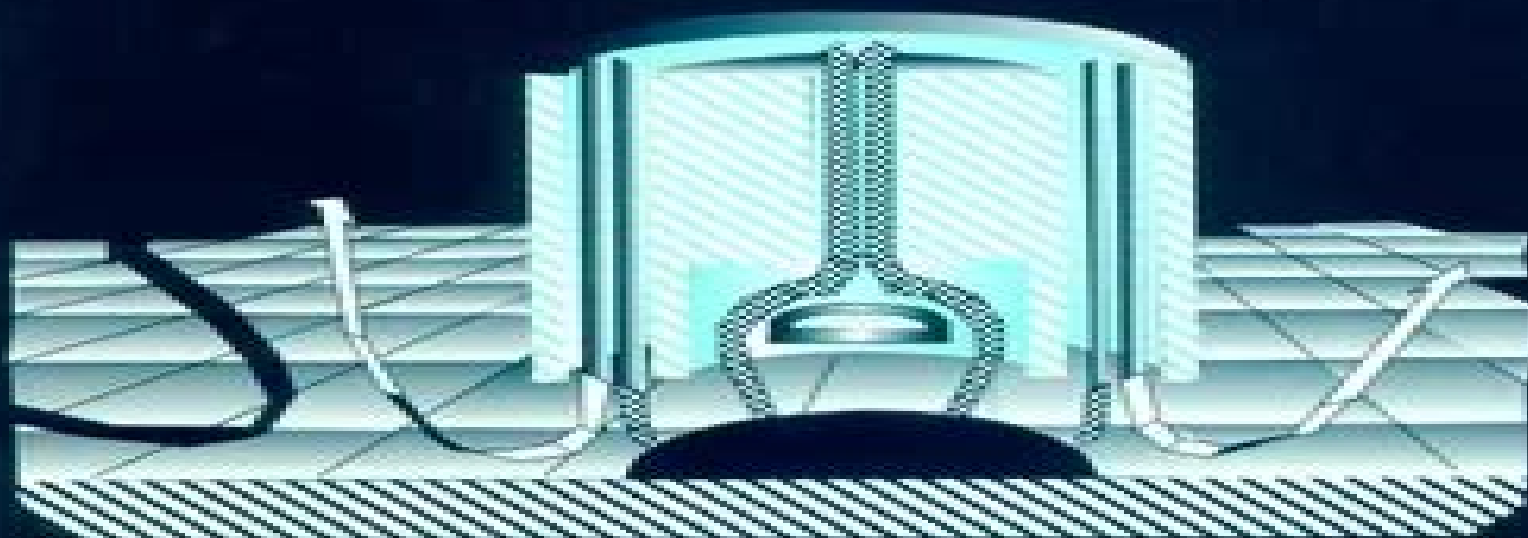


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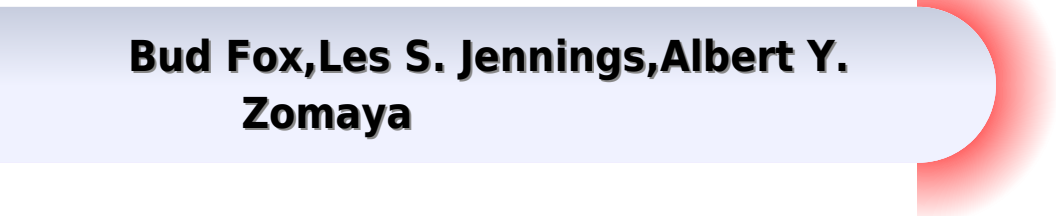
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**Bud Fox, Les S. Jennings, Albert Y.
Zomaya**



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Adaptive Mobile Robotics - Proceedings Of The 15th International Conference On Climbing And Walking Robots And The Support Technologies For Mobile Machines

Mohammad Osman Tokhi, Noah J Cowan, Abul K M Azad, Gurvinder S Virk, Roger D Eastman, 2012-07-11 This book provides state of the art scientific and engineering research findings and developments in the area of mobile robotics and associated support technologies The book contains peer reviewed articles presented at the CLAWAR 2012 conference Robots are no longer confined to industrial manufacturing environments A great deal of interest is invested in the use of robots outside the factory environment The CLAWAR conference series established as a high profile international event acts as a platform for dissemination of research and development findings and supports such a trend to address the current interest in mobile robotics to meet the needs of mankind in various sectors of the society These include personal care public health services in the domestic public and industrial environments The editors of the book have extensive research experience and publications in the area of robotics in general and in mobile robotics specifically and their experience is reflected in editing the contents of the book

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Active Sensors For Local Planning In Mobile Robotics Penelope Probert Smith, 2001-12-05 This book describes recent work on active sensors for mobile robots An active sensor interacts with its surroundings to supply data on demand for a particular function gathering and abstracting information according to need rather than acting as a generic data gatherer Details of the physical operation are hidden The book deals mainly with active range sensors which provide rapid information for local planning describing extraction of two dimensional features such as lines corners and cylinders to reconstruct a plan of a building It is structured according to the physical principles of the sensors since to a large extent these determine the

function of the sensors and the methods of processing Recent work using sonar optoelectronic sensors and radar is described Sections on vision and on sensor management develop the idea of software adaptation for efficient operation in a changing environment

Electronic Nose Technologies and Advances in Machine Olfaction Albastaki, Yousif Abdullatif, Albalooshi, Fatema, 2018-04-13 The design and study of materials is a pivotal component to new discoveries in the various fields of science and technology By better understanding the components and structures of materials researchers can increase its applications across different industries Electronic Nose Technologies and Advances in Machine Olfaction is an academic scholarly resource that examines the emerging applications of odor sensing devices as well as a better understanding of the designing process with the aid of neural networks and various other technologies Featuring coverage on a broad range of topics including food spoilage detection chemical sensing and olfactometer this book is a vital resource for engineers academicians researchers students and practitioners seeking current research on the advancements in applications of odor sensing devices

Experimental Robotics Oussama Khatib, Vijay Kumar, George Pappas, 2009-03-28 By the dawn of the new millennium robotics has undergone a major transformation in scope and dimensions This expansion has been brought about by the maturity of the field and the advances in its related technologies From a largely dominant industrial focus robotics has been rapidly expanding into the challenges of the human world The new generation of robots is expected to safely and dependably co habitat with humans in homes workplaces and communities providing support in services entertainment education healthcare manufacturing and assistance Beyond its impact on physical robots the body of knowledge robotics has produced is revealing a much wider range of applications reaching across diverse research areas and scientific disciplines such as biomechanics haptics neurosciences virtual simulation animation surgery and sensor networks among others In return the challenges of the new emerging areas are proving an abundant source of stimulation and insights for the field of robotics It is indeed at the intersection of disciplines that the most striking advances happen The goal of the series of Springer Tracts in Advanced Robotics STAR is to bring in a timely fashion the latest advances and developments in robotics on the basis of their significance and quality It is our hope that the wider dissemination of research developments will stimulate more exchanges and collaborations among the research community and contribute to further advancement of this rapidly growing field

Wavelets In Soft Computing Marc Thuillard, 2001-06-15 This book presents the state of integration of wavelet theory and multiresolution analysis into soft computing It is the first book on hybrid methods combining wavelet analysis with fuzzy logic neural networks or genetic algorithms Much attention is given to new approaches fuzzy wavelet that permit one to develop using wavelet techniques linguistically interpretable fuzzy systems from data The book also introduces the reader to wavelet based genetic algorithms and multiresolution search A special place is given to methods that have been implemented in real world applications particularly the different techniques combining fuzzy logic or neural networks with wavelet theory

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Jennings,Albert Y Zomaya,2000-09-04 This book introduces a practical approach to the modelling and computation of real world systems Multibody dynamics planar and spatial modelling and numerical methods are all pursued to obtain information about the behaviour of various dynamical systems Each study presents the method of modelling and the ensuing differential equations governing the system behaviour Integration of the equations yields results which are carefully discussed and which indicate how useful information may be obtained from the study The studies include planar mechanisms heavy equipment automobile crash simulation and a spatial planetary system example Research students scientists and engineers will appreciate the practical approach taken in this book Constrained Dynamics Computations Bud Fox,Les S. Jennings,Albert

Y. Zomaya,2000 This book introduces a practical approach to the modelling and computation of real world systems Multibody dynamics planar and spatial modelling and numerical methods are all pursued to obtain information about the behaviour of various dynamical systems Each study presents the method of modelling and the ensuing differential equations governing the system behaviour Integration of the equations yields results which are carefully discussed and which indicate how useful information may be obtained from the study The studies include planar mechanisms heavy equipment automobile crash simulation and a spatial planetary system example Research students scientists and engineers will appreciate the practical approach taken in this book Distributed Autonomous Robotic Systems 8 Hajime Asama,Haruhisa Kurokawa,Jun

Ota,Kosuke Sekiyama,2009-05-15 The International Symposia on Distributed Autonomous Robotic Systems DARS started at Riken Japan in 1992 Since then the DARS symposia have been held every two years in 1994 and 1996 in Japan Riken Wako in 1998 in Germany Karlsruhe in 2000 in the USA Knoxville TN in 2002 in Japan Fukuoka in 2004 in France Toulouse and in 2006 in the USA Minneapolis MN The 9th DARS symposium which was held during November 17 19 in T kuba Japan hosted 84 participants from 13 countries The 48 papers presented there were selected through rigorous peer review with a 50% acceptance ratio Along with three invited talks they addressed the spreading research fields of DARS which are classifiable along two streams theoretical and standard studies of DARS and interdisciplinary studies using DARS concepts The former stream includes multi robot cooperation task assignment methodology among multiple robots multi robot localization etc swarm intelligence and modular robots The latter includes distributed sensing mobiligence ambient intelligence and mul agent systems interaction with human beings This book not only offers readers the latest research results related to DARS from theoretical studies to application oriented ones it also describes the present trends of this field With the diversity and depth revealed herein we expect that DARS technologies will flourish soon

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