PROGRAMMABLE AUTOMOTION TECHNOLOGIES

An Introduction to CNC, Robotics and PLCs







Daniel E. Kandray, P.E.

Khosrow-Pour, D.B.A., Mehdi

Programmable Automation Technologies Daniel Kandray,2010 The text is organized into four sections Section One is introductory Chapter 1 provides some background on manu facturing and defines programmable automation Chapter 2 explains calculation methods used to justify automation expenditures as motivated by productivity concepts Section Two covers computer numerical control Chapter Chapter 3 introduces CNC technology Chapter 4 discusses CNC programming and Chapter 5 addresses CNC simulation Robotics is covered in Section Three Chapter 6 introduces robotics technology and Chapter 7 goes over both robotics programming and simulation Section Four addresses PLCs Chapter 8 introduces PLCs and Chapter 9 covers programming and simulation of PLCs Finally Chapter 10 concludes the text with a discussion of how all three technologies are brought together to create programmable automated workstations and work cells Book Jacket

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