

CSE3013 - "Artificial Intelligence"

Uncertainty and Knowledge Reasoning

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AI

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Introduction



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What is Uncertainty?

It is a state of

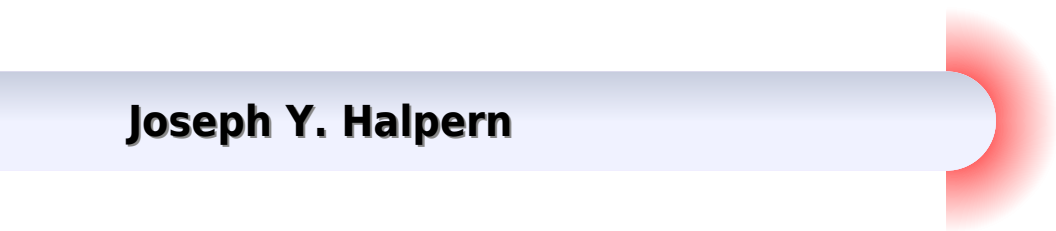
- Doubt about the future or
- About what is the right thing to do.

Examples :

- A doctor does not know exactly what is going on inside a patient.
- A teacher does not know exactly what a student understands,
- A robot does not know what is in a room it left a few minutes ago.
- A period of Politician

Reasoning With Uncertainty In Robotics Springer2008 Paperback

Joseph Y. Halpern



Reasoning With Uncertainty In Robotics Springer 2008 Paperback:

The Argumentative Turn in Policy Analysis Sven Ove Hansson, Gertrude Hirsch Hadorn, 2016-05-26 This book describes argumentative tools and strategies that can be used to guide policy decisions under conditions of great uncertainty. Contributing authors explore methods from philosophical analysis and in particular argumentation analysis showing how it can be used to systematize discussions about policy issues involving great uncertainty. The first part of the work explores how to deal in a systematic way with decision making when there may be plural perspectives on the decision problem along with unknown consequences of what we do. Readers will see how argumentation tools can be used for prioritizing among uncertain dangers for determining how decisions should be framed for choosing a suitable time frame for a decision and for systematically choosing among different decision options. Case studies are presented in the second part of the book showing argumentation in practice in the areas of climate geoengineering, water governance, synthetic biology, nuclear waste, and financial markets. In one example, argumentation analysis is applied to proposals to solve the climate problem with various technological manipulations of the natural climate system such as massive dispersion of reflective aerosols into the stratosphere. Even after a thorough investigation of such a proposal, doubt remains as to whether all the potential risks have been identified. In such discussions, conventional risk analysis does not have much to contribute since it presupposes that the risks have been identified, whereas the argumentative approach to uncertainty management can be used to systematize discussions.

Integrierte Multi-Sensor-Fusion für die simultane Lokalisierung und Kartenerstellung für mobile Robotersysteme Emter, Thomas, 2021-06-17 In der vorliegenden Arbeit werden probabilistische Methoden für die Kombination mehrerer Sensoren mittels Multi Sensor Fusion für die robuste und präzise Lokalisierung und Kartenerstellung in heterogenen Außenumgebungen vorgestellt. Es werden sowohl Aspekte der robusteren Wiedererkennung von Landmarken als auch die Integration zusätzlicher absoluter und relativer Sensoren mittels erweiterter Filterverfahren beleuchtet. In this work, probabilistic methods for combining multiple sensors utilizing multi sensor fusion for robust and precise localization and mapping in heterogeneous outdoor environments are presented. Aspects of increasing the reliability of landmark recognition are highlighted as well as the integration of additional absolute and relative sensors using advanced filtering techniques.

Methoden wissensbasierter Systeme Christoph Beierle, Gabriele Kern-Isberner, 2014-09-15 Von namhaften Professoren empfohlen. State of the Art bietet das Buch zu diesem klassischen Bereich der Informatik. Die wesentlichen Methoden wissensbasierter Systeme werden verständlich und anschaulich dargestellt. Repräsentation und Verarbeitung sicheren und unsicheren Wissens in maschinellen Systemen stehen dabei im Mittelpunkt. Ein Online Service mit ausführlichen Musterlösungen erleichtert das Lernen.

Advances and Applications of DSMT for Information Fusion. Collected Works, Volume 5 Florentin Smarandache, Jean Dezert, Albena Tchamova, This fifth volume on Advances and Applications of DSMT for Information Fusion collects theoretical and applied contributions of researchers working in different fields of

applications and in mathematics and is available in open access The collected contributions of this volume have either been published or presented after disseminating the fourth volume in 2015 available at fs.unm.edu/DSmTbook4.pdf or www.onera.fr/sites/default/files/2015-DSmTBook4.pdf in international conferences seminars workshops and journals or they are new The contributions of each part of this volume are chronologically ordered First Part of this book presents some theoretical advances on DSmT dealing mainly with modified Proportional Conflict Redistribution Rules PCR of combination with degree of intersection coarsening techniques interval calculus for PCR thanks to set inversion via interval analysis SIVIA rough set classifiers canonical decomposition of dichotomous belief functions fast PCR fusion fast inter criteria analysis with PCR and improved PCR5 and PCR6 rules preserving the quasi neutrality of quasi vacuous belief assignment in the fusion of sources of evidence with their Matlab codes Because more applications of DSmT have emerged in the past years since the apparition of the fourth book of DSmT in 2015 the second part of this volume is about selected applications of DSmT mainly in building change detection object recognition quality of data association in tracking perception in robotics risk assessment for torrent protection and multi criteria decision making multi modal image fusion coarsening techniques recommender system levee characterization and assessment human heading perception trust assessment robotics biometrics failure detection GPS systems inter criteria analysis group decision human activity recognition storm prediction data association for autonomous vehicles identification of maritime vessels fusion of support vector machines SVM Silx Furtif RUST code library for information fusion including PCR rules and network for ship classification Finally the third part presents interesting contributions related to belief functions in general published or presented along the years since 2015 These contributions are related with decision making under uncertainty belief approximations probability transformations new distances between belief functions non classical multi criteria decision making problems with belief functions generalization of Bayes theorem image processing data association entropy and cross entropy measures fuzzy evidence numbers negator of belief mass human activity recognition information fusion for breast cancer therapy imbalanced data classification and hybrid techniques mixing deep learning with belief functions as well

Choice, 2008 Reasoning about Uncertainty in Robot Motion Planning Anthony Lazanas, 1994 Experimentation with the algorithm using a real mobile robot has been successful By engineering the workspace we have been able to satisfy all the assumptions of our planning model As a result the robot has been able to operate for long periods of time with no failures *Reasoning about Uncertainty* Joseph Y. Halpern, 2003

High level reasoning considering uncertainty for a service robot with human-robot interaction Sven R. Schmidt-Rohr, 2006 Robotic Navigation and Spatial Reasoning in Uncertain Environments with a Navigation Mesh Michal Stolba, 2010

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